

Amy LaViers

CONTACT INFORMATION	amy@theradlab.xyz Philadelphia, PA, USA	www.theradlab.xyz www.amylaviers.com
APPOINTMENTS	The Robotics, Automation, and Dance (RAD) Lab , Philadelphia, PA ◊ Director May 2013 – present	
	Anticipation Ventures, LLC , Philadelphia, PA ◊ Philanthropy Lead February 2020 – present	
	Soma Measure, Inc , Philadelphia, PA ◊ Co-founder, CEO/CTO August 2020 – December 2021	
	CAAIL, LLC , Urbana, IL ◊ Co-founder, CCO/CTO September 2018 – August 2020	
	University of Illinois , Urbana, IL ◊ Mechanical Science and Engineering Department August 2015 – August 2020 Assistant Professor	
	AE Machines, Inc , Champaign, IL ◊ Co-founder, CTO June 2015 – August 2019	
	University of Virginia , Charlottesville, VA ◊ Systems and Information Engineering Department August 2013 – May 2015 Assistant Professor	
EDUCATION	Laban/Bartenieff Institute of Movement Studies , New York, NY ◊ C.M.A. Laban Movement Studies August 2016 THESIS: <i>Preparing to Cook: Function and Expression Within Recipe</i> ADVISER: Professor Karen Bradley	
	Georgia Institute of Technology , Atlanta, GA ◊ Ph.D., Electrical and Computer Engineering August 2013 THESIS: <i>Choreographic Abstractions for Style-Based Robotic Motion</i> ADVISER: Professor Magnus Egerstedt MAJOR AREA OF STUDY: Systems and Control MINOR AREA OF STUDY: Mathematics	
	◊ M.S., Electrical and Computer Engineering December 2010	
	Princeton University , Princeton, NJ ◊ B.S.E., Mechanical and Aerospace Engineering June 2009 THESIS: <i>Learning the Primary Colors of Dance</i> ADVISER: Professor Naomi Leonard	
	◊ Certificate in Dance June 2009 THESIS: <i>Pleiades</i> Performed at the Berlind Theater, March 2009. ADVISER: Rebecca Lazier	

BOOKS

- A. LaViers and C. Maguire. *Making Meaning With Machines: Somatic Strategies, Choreographic Technologies, and Notational Abstractions Through a Laban/Bartenieff Lens*. MIT Press. 2023.
- A. LaViers and M. Egerstedt. (Eds.) *Controls and Art: Inquires that Intersect the Subjective and the Objective*. Springer. 2014.

BOOK CHAPTERS

- K. Ladenheim, A. LaViers, and C. Maguire. “Breathing With Robots: Notating Performer Strategy, Alongside Choreographer Intent and Audience Observation, In Breath-driven Robotic Dance Performance” *Modeling Visual Aesthetics, Emotion, and Artistic Style* J. Wang and R. Adams. (Eds). (In progress at Springer, expected 2023.)
- A. LaViers. “First Encounters with Robots Through Embodied Observation, Imagined Narrative, and Choreography” *Materializing Digital Futures: Touch, Movement, Sound and Vision* T. Cinque and J. B. Vincent (Eds). 169-185. 2022.
- A. LaViers. “Programmed Improvisation Inspired From Autonomous Humanoids.” 513-526, Chapter in *Handbook of Improvisation in Dance*. V. Midgelow (Ed.) Oxford University Press. 2019.
- A. LaViers, A. Bashiri, Y. Sheng, J. Heddy, and L. Bai. “Abstractions for Design-by-Humans of Heterogeneous Autonomous Behaviors.” 237-262, Chapter in *Dance Notations and Robot Motion*. J.P. Laumond and N. Abe (Eds.) Springer Tracts in Advanced Robotics (STAR). 2015.
- A. LaViers, L. Teague, and M. Egerstedt. “Style-based Robotic Motion in Contemporary Dance Performance” 205-229, Chapter in *Controls and Art: Inquires that Intersect the Subjective and the Objective*. A. LaViers and M. Egerstedt (Eds.) Springer. 2014.

JOURNAL PUBLICATIONS

- A. LaViers. “Robotics and Dance” *Annual Review of Control, Robotics, and Autonomous Systems*. (invited submission, in progress)
- A. Bushman and A. LaViers. “Toward Human-like Teleoperated Robot Motion: Evaluation of Motion Generated from a Choreography-inspired Method for Joint-space Control of Articulated Robots in Static and Dynamic Tasks” (in progress)
- K. Ladenheim and A. LaViers. “Babyface: Performance and Installation Art Exploring the Feminine Ideal in Gendered Machines.” *The Art of Human-Robot Interaction: Creative Perspectives from Design and the Arts* Topic in *Frontiers in Robotics and AI*, Section *Human-Robot Interaction*. D. C. Herath, E. A. Jochum, C. Kroos, D. St-Onge (Eds). 8. 1-21. 2021.
- A. Bacula and A. LaViers. “Character Recognition on a Varied Robotic Platforms via a Laban Movement Analysis in Expert and Lay Groups.” *International Journal on Social Robotics (SORO)*. 13(5), 1047-1062. 2020.
- C. Cuan, E. Berl, and A. LaViers. “Measuring Human Perceptions of Expressivity in Natural and Artificial Systems Through the Live Performance Piece *Time to Compile*.” *Paladyn. Journal of Behavioral Robotics. (Special Issue on Social Robots in Therapy: Focusing on Autonomy and Ethical Challenges)*. 10(1), 364-379. 2019.
- R. Kaushik and A. LaViers. “Imitation of Human Motion by Low Degree-of-Freedom Simulated Robots and Human Preference for Mappings Driven by Spinal, Arm, and Leg Activity.” *International Journal on Social Robotics (SORO)*. 11(5), 765-782. 2019.

- C. Cuan, E. Berl, and A. LaViers. “*Time to Compile: A Performance Installation as Human-Robot Interaction Study Examining Self-Evaluation and Perceived Control Through the Lenses of Movement and Technology Literacy and Valence.*” *Paladyn. Journal of Behavioral Robotics. (Special Issue on Social Robots in Therapy: Focusing on Autonomy and Ethical Challenges)*. 10(1), 267-285. 2019.
- A. Jang Sher, U. Huzaifa, J. Li, V. Jain, A. Zurawski, and A. LaViers. “An Embodied, Platform-invariant Architecture for Connecting High-level Spatial Commands to Platform Articulation.” *Robotics and Autonomous Systems (RAS)*. 119, 263-277. 2019.
- A. LaViers. “Ideal Mechanization: Exploring the Machine Metaphor Through Theory and Performance.” *Arts (Special Issue on Machine as Artist for the 21st Century)*. MDPI. 8(2), 67. 2019.
- A. LaViers. “Counts of Mechanical, External Configurations Compared to Computational, Internal Configurations in Natural and Artificial Systems.” *PLoS ONE*. 14(5): e0215671. 2019.
- U. Huzaifa, C. Maguire, and A. LaViers. “Toward an Expressive Bipedal Robot: Variable Gait Synthesis and Validation in a Planar Model.” *International Journal on Social Robotics (SORO)*. 12(1), 129-141. 2019.
- H. Cui, C. Maguire, and A. LaViers. “Laban-Inspired Task-Constrained Expressive, Variable Motion Generation on Aerial Robots.” *Robotics*. MDPI. 8(2), 24. 2019.
- M. Heimerdinger and A. LaViers. “Modeling the Interactions of Context and Style on Affect in Motion Perception: Stylized Gaits Across Multiple Environmental Contexts.” *International Journal on Social Robotics (SORO)*. 11(3), 495-513. 2019.
- A. LaViers, C. Cuan, C. Maguire, K. Bradley, K. Brooks Mata, A. Nilles, I. Vidrin, N. Chakraborty, M. Heimerdinger, U. Huzaifa, R. McNish, I. Pakrasi, and A. Zurawski, “Choreographic and Somatic Approaches for the Development of Expressive Robotic Systems,” *Arts (Special Issue on Machine as Artist for the 21st Century)* MDPI. 7(2), 11. 2018.
- T. Marino, C. Widdowson, A. Oetting, A. Lakshmanan, H. Cui, N. Hovakimyan, R. Wang, A. Kirlik, A. LaViers, D. Stipanovic. “Carebots: Prolonged Elderly Independence Using Small Mobile Robots.” *ASME Mechanical Engineering Magazine*. 138(9), S8-S13. 2016.
- A. LaViers, Y. Chen, C. Belta, and M. Egerstedt. “Automatic Sequencing of Ballet Poses: A Formal Approach to Phrase Generation.” *IEEE Robotics and Automation Magazine*. 18(3), 87-95. Sept. 2011.
- A. LaViers and C. Maguire. “The BESST System: Explicating a New Component of Time in Laban/Bartenieff Movement Studies Through Work With Robots.” *78th International Conference on Movement and Computing (MOCO)*. 40. Chicago, IL. 2022.
- C. Fuller, U. Huzaifa, A. LaViers, and J. Schultz. “Core-centered actuation for Biped Locomotion of Humanoid Robots.” *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. 3481-3487. Virtual from Las Vegas, NV. 2020.

PEER-REVIEWED
CONFERENCE
PROCEEDINGS

- A. LaViers and I. Vidrin. “Can a Robot Do a Trust Fall? Absurdity as a Component of Human Intelligence and Embodiment.” *Eleventh International Conference on Computational Creativity (ICCC)*. Virtual from Lisbon, Portugal. 2020.
- R. Kaushik, A. K. Mishra (Siemens), and A. LaViers. “Feasible Stylized Motion: Robotic Manipulator Imitation of a Human Demonstration with Collision Avoidance and Style in Increasingly Cluttered Environments.” *7th International Conference on Movement and Computing (MOCO)*. 4. Virtual from Jersey City, NJ. 2020.
- C. Cuan, J. Hoffswell, and A. LaViers. “Stories About the Future: An Initial Dataset Exploring How Co-movement with Robots Affects Perceptions About Robot Capability.” *7th International Conference on Movement and Computing (MOCO)*. 10. Virtual from Jersey City, NJ. 2020.
- K. Ladenheim and A. LaViers. “Babyface.” *7th International Conference on Movement and Computing (MOCO)*. 34. Virtual from Jersey City, NJ. 2020. (Practice Work; Extended Abstract)
- A. Bushman, M. Asselmeier, J. Won, and A. LaViers. “Toward Human-like Teleoperated Robot Motion: Performance and Perception of a Choreography-inspired Method in Static and Dynamic Tasks for Rapid Pose Selection of Articulated Robots” *IEEE International Conference on Robotics and Automation (ICRA)*. 10219-10225. Virtual from Paris, France. 2020.
- K. Ladenheim, R. McNish, W. Rizvi, and A. LaViers. “Motion-activated Wearable Robot for Live Dance Performance Investigating the Feminine Cyborg Metaphor” *15th Annual ACM/IEEE International Conference on Human Robot Interaction (HRI)*. 243-251. Cambridge, UK. 2020.
- W. Rizvi, I. Pakrasi, and A. LaViers. “Influence of Variable Environments and Character-Specific Design on Perception of Virtual Robots with Affective Labels.” *International Conference on Social Robotics (ICSR)*. 256-266. Madrid, Spain, 2019.
- E. Berl, I. Pakrasi, and A. LaViers. “Creating Context Through Performance: Perception of the ‘DD’ Robotic Platform in Variable Valence Interactions in Distinct Office Environments.” *International Conference on Social Robotics (ICSR)*. 288-298. Madrid, Spain, 2019.
- U. Huzaifa, C. Fuller, J. Schultz, and A. LaViers. “Toward a Bipedal Robot with Variable Gait Styles: Sagittal Forces Analysis in a Planar Simulation and a Prototype Ball-Tray Mechanism.” *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. 2266-2272. Macau, China, 2019.
- J. Lambert, W. Rizvi, U. Huzaifa, and A. LaViers. “A Comparison of Descriptive and Emotive Labels to Explain Human Perception of Gait Styles on a Compass Walker in Variable Contexts.” *28th IEEE International Conference on Robot and Human Interactive Communication (RO-MAN)*. 1-8. New Dehli, India, 2019.
- Y. Zhou, M. Asselmeier, and A. LaViers. “Toward Expressive Multi-Platform Teleoperation: Laban-Inspired Concurrent Operation of Multiple Joints on the Rethink Robotics Baxter Robot in Static and Dynamic Tasks.” *6th International Conference on Movement and Computing (MOCO)*. 15. Tempe, AZ, 2019.
- W. Rizvi, I. Pakrasi, and A. LaViers. “Movement Design of Virtual Aerial Robots with Distinct Affective Labels.” *6th International Conference on Movement and Computing (MOCO)*. 27. Tempe, AZ, 2019. (Extended Abstract)

- R. Kaushik and A. LaViers. “Imitating Human Movement Using a Measure of Verticality to Animate Low Degree-of-Freedom Non-humanoid Virtual Characters.” *International Conference on Social Robotics (ICSR)*. 588-598. Qingdao, China, 2018.
- I. Pakrasi, N. Chakraborty, C. Cuan, E. Berl, W. Rizvi, and A. LaViers. “Dancing Droids: An Expressive Layer for Mobile Robots Developed Within Choreographic Practice.” *International Conference on Social Robotics (ICSR)*. 410-420. Qingdao, China, 2018.
- C. Cuan, I. Pakrasi, and A. LaViers “Perception of Control in Artificial and Human Systems: A Study of Embodied Performance Interactions.” *International Conference on Social Robotics (ICSR)*. 503-512. Qingdao, China, 2018.
- A. Bacula and A. LaViers. “Character Design and Validation on Aerial Robotic Platforms Using Laban Movement Analysis.” *International Conference on Social Robotics (ICSR)*. 202-212. Qingdao, China, 2018.
- C. Cuan, I. Pakrasi, E. Berl, and A. LaViers “CURTAIN and Time to Compile: A Demonstration of an Experimental Testbed for Human-Robot Interaction.” *27th IEEE International Conference on Robot and Human Interactive Communication (RO-MAN)*. 255-261. Nanjing, China, 2018.
- C. Cuan, I. Pakrasi, and A. LaViers, “Time to Compile.” *5th International Conference on Movement and Computing (MOCO)*. 53. Genoa, Italy 2018. (Practice Work; Extended Abstract)
- A. Nilles, C. Gladish, M. Beckman, and A. LaViers, “Improv: Live Coding for Robot Motion Design.” *5th International Conference on Movement and Computing (MOCO)*. 43. Genoa, Italy, 2018. (Extended Abstract)
- A. Bacula and A. LaViers, “Character Recognition on a Humanoid Robotic Platform via a Laban Movement Analysis.” *5th International Conference on Movement and Computing (MOCO)*. 17. Genoa, Italy, 2018.
- I. Pakrasi, N. Chakraborty, and A. LaViers, “A Design Methodology for Abstracting Character Archetypes onto Robotic Systems.” *5th International Conference on Movement and Computing (MOCO)*. 24. Genoa, Italy, 2018.
- R. Kaushik, I. Vidrin, and A. LaViers, “Quantifying Coordination in Human Dyads via a Measure of Verticality,” *5th International Conference on Movement and Computing (MOCO)*. 19. Genoa, Italy, 2018.
- C. Cuan, I. Pakrasi., and A. LaViers, “*Time to Compile: An Interactive Art Installation*”, *Intersections: 16th Biennial Symposium*. 19-24. The Ammerman Center for Arts and Technology. New London, CT. 2018.
- U. Huzaifa and A. LaViers. “Producing Multiple Movement Executions Leveraging Embodied Movement Strategies and Platform Symmetry.” *IEEE International Conference on Robotics and Biomimetics (ROBIO)*. 1460-1467. Macao, China. 2017
- M. Heimerdinger and A. LaViers. “Influence of Environmental Context on Recognition Rates of Stylized Walking Sequences.” *Ninth International Conference on Social Robotics (ICSR)*. 272-282. Tsukuba, Japan. 2017.
- L. Dahl, J. Bellona, L. Bai, and A. LaViers. “Data-driven Design of Sound for Enhancing the Perception of Expressive Robotic Movement.” *Proceedings of the 4th International Conference on Movement Computing (MOCO)*. 16. London, UK. 2017.

- J. Bellona, L. Bai, L. Dahl, and A. LaViers. “Empirically Informed Sound Synthesis Application for Enhancing the Perception of Expressive Robotic Movement” *The 23rd International Conference on Auditory Display (ICAD)*. 73-80. State College, PA. 2017.
- U. Huzaifa and A. LaViers. “Control Design for Planar Model of a Core-located Actuation Walker.” *6th IEEE International Conference on Biomedical Robotics and Biomechanics (BioRob)*. 170-175. Singapore. 2016.
- U. Huzaifa, C. Bernier, Z. Calhoun, C. Kohout, J. Heddy, B. Libowitz, A. Moening, J. Ye, C. Maguire, and A. LaViers. “Embodied Movement Strategies for Development of a Core-located Actuation Walker.” *6th IEEE International Conference on Biomedical Robotics and Biomechanics (BioRob)*. 176-181. Singapore. 2016. (Best Poster Finalist)
- S. Huber, J. McAuliff, K. Monson, T. O’Brien, J. Valdez, and A. LaViers. “Exploration of robotic system design in improving the patient experience in physical therapy sessions at the UVA Children’s Hospital.” *Systems and Information Engineering Design Symposium (SIEDS)*. 230-235. 2015.
- G. Heddy, U. Huzaifa, P. Beling, Y. Haimes, J. Marvel, B. Weiss, A. LaViers. “Linear Temporal Logic (LTL) Based Monitoring of Smart Manufacturing Systems.” *Annual Conference of the PHM Society*. 6. 2015.
- M. Malinowski, P. Beling, Y. Haimes, A. LaViers, J. Marvel, B. Weiss. “System Interdependency Modeling in the Design of Prognostic and Health Management Systems in Smart Manufacturing.” *Annual Conference of the PHM Society*. 6. 2015.
- B. Choo, P. Beling, A. LaViers, J. Marvel, B. Weiss. “Adaptive Multi-Scale PHM for Robotic Assembly Processes.” *Annual Conference of the PHM Society*. 6. 2015.
- L. Bobadilla, T. T. Johnson, A. LaViers, and U. Huzaifa. “Verified Planar Formation Control Algorithms by Composition of Primitives.” *AIAA Guidance, Navigation, and Control (GNC) Conference, AIAA Science and Technology Forum (SciTech)*. 1541. Orlando, FL. 2015.
- Y. Sheng and A. LaViers. “Style-based Segmentation of Human Motion.” *IEEE International Conference on Systems Man and Cybernetics (SMC)*. 240-245. San Diego, CA. Oct. 2014.
- K. Green, A. Panchang, H. Meng, E. D’Agostini, R. Bates, R. Bailey, A. LaViers. “Fluid handling and environmental management for automated 3-D cell culturing.” *Systems and Information Engineering Design Symposium (SIEDS)*. 12-17. May 2014.
- A. LaViers and M. Egerstedt. “Style-based Abstractions for Human Motion Classification.” *ACM/IEEE Fifth International Conference on Cyber-Physical Systems (ICCPS)*. 84-91. Berlin, Ger, Apr. 2014.
- A. LaViers and M. Egerstedt. “Style Based Robotic Motion.” *American Control Conference (ACC)*. 4327-4332. Montreal, CAN, Jun. 2012.
- A. LaViers, Y. Chen, C. Belta, and M. Egerstedt. “A Formal Approach to the Automatic Generation of Balletic Motions.” *ACM/IEEE Second International Conference on Cyber-Physical Systems (ICCPS)*. 13-21. Chicago, IL, Apr. 2011.

A. LaViers and M. Egerstedt. “The Ballet Automaton: A Formal Model for Human Motion.” *American Control Conference (ACC)*. 3837-3842. San Francisco, CA, Jun. 2011.

A. LaViers, A. Rahmani, and M. Egerstedt. “Dynamic Spectral Clustering.” *Mathematical Theory of Networks and Systems (MTNS)*. 747-750. Budapest, Hungary, July 2010.

ARTICLES AND
ESSAYS

A. LaViers and I. Vidrin. “What falling robots reveal about the absurdity of human trust.” Ed. Sam Dresser *Psyche*. March 15, 2021.

A. LaViers. “Dancing with Robots: Choreography brings new perspectives on encoding expressive motion into machines.” *Scientific American*. July-August 2020.

A. LaViers. “Sure, it can backflip – but can a robot hold down a desk job?” Ed. Sam Dresser *Aeon*. Feb. 4, 2019.

A. LaViers. “Make robot motions natural: Humanoid machines should move and gesture more like us, argues Amy LaViers.” *Nature*. 565, 422-424. 2019.

A. LaViers. “Engineering Needs Qualitative Methods.” *Medium*. 2017.

A. LaViers, H. Cui, M. Heimerdinger, U. Huzaiifa, A. Jang Sher, A. Nilles, and I. Pakrasi. “Expressivity Expansion Pack” for the *The Robot Design Game*. 2017.

A. LaViers. “TA--ing for Trolls: A Surprising Contrast Between MOOCs and Traditional, Brick and Mortar Classrooms.” *Educational Corner. ASME Dynamic Systems & Control Division (DSCD) Newsletter*. Fall 2013.

CHOREOGRAPHY
AND ART
INSTALLATIONS

Barnard College at Columbia University, New York, NY November 2021
Media Movement Salon (MeMoSa) at the Barnard Movement Lab at Columbia University, presenting *Babyface* with artist-in-residence Kate Ladenheim during a week-long residency. (Rescheduled and expanded from March 2020.)

CAPTIVITY – EdgeCut Performance Series, Online October 2020

Presenting a native online version of *Babyface* with Kate Ladenheim for the theme CAPTIVITY in a series curated by Heidi Boisvert and Kat Mustatea. Co-presented by Edgecut Arts and New York Live Arts on the 3-D online meeting platform Nowhere.

Bespoke, interactive online performance application with with artist-in-residence Kate Ladenheim

★ *Babyface*

The Majestic Theater via Zoom, Corvallis, OR

Singu-Hilarity, A Robot and Human Comedy Show July 2020

Virtual performance with with artist-in-residence Kate Ladenheim

★ *Babyface*

Mana Contemporay via Zoom, Jersey City, NJ

7th International Conference on Movement and Computing (MOCO) July 2020

Virtual performance with with artist-in-residence Kate Ladenheim

★ *Babyface*

Circuit Circus, Urbana, IL [Canceled, COVID-19]
Illinois Program in Research in the Humanities (IPRH) sponsored participatory performance event, co-organized with Dance Department faculty John Toenjes; event was canceled in light of COVID-19 measures.

The Granoff Center for Creative and Performance Arts, Brown University, Providence, RI

Conference on Research on Choreographic Interfaces (CRCI) March 2020
Presented robot augmented solo with artist-in-residence Kate Ladenheim
★ *Babyface*

The Performance Arcade, Wellington, NZ

Annual public art series on the Wellington Waterfront February 2020
Work by The People Movers x The RAD Lab with associated research study pilot design with Footnote New Zealand Dance Company, presenting with artist-in-residence Kate Ladenheim and supported by the US Embassy
★ *Babyface*

University of California – Santa Barbara, Santa Barbara, CA

Concert work within the Alliance of Women in Media Arts and Sciences Conference (AWMAS) conference program February 2020
Work by The People Movers x The RAD Lab, presented live by artist-in-residence Kate Ladenheim.
★ *Babyface*

CODAME Art+Tech Festival, San Francisco, CA

GitHub October 2019
Choreographed in collaboration with Catie Cuan and Cat Maguire. Set piece on two dancers from RAW Dance SF. Created an “open source” repository (on github.com) that provides instructions, code, and movement scores that allow others to perform the same piece.
★ *arubina*

The Gallery in Stauffer B, Arizona State University, Tempe, AZ

6th International Conference on Movement and Computing (MOCO) October 2019
Choreographed and performed in an interactive piece, accepted to the conference after peer review as a Practice Work.
★ *A Machine.*

Joe’s Pub at the Public Theater, New York, NY

Dance NOW Festival September 2019
Led collaboration between artist-in-residence Kate Ladenheim (The People Movers), research technician Reika McNish, and student Wali Rizvi for the development of a machine-augmented solo.
★ *Babyface*

Robotics, Automation, and Dance (RAD) Lab, Urbana, IL

In Progress Showing August 2019
Hosted choreographer Kade Ladenheim (The People Movers) to collaborate on artistic piece and research with students Reika McNish and Wali Rizvi. Advised choreographic and technical development for a solo performed by Kate with a machine-augmented costume, a pair of breath-sensing wings. The in progress showing was open to the public and advertised by MechSE Department.
★ *Babyface*

Mountain Arts Center, Prestonsburg, KY

Free public event co-sponsored by the East Kentucky Science Center June 2019

Robotic art installation developed and performed with Catie Cuan, with simultaneous user study around the Future of Work, probing perceptions about robots through a non-literal, theatrical embodied movement experience.

★ *Stories About the Future*

Tango on Water, Charlottesville, VA

Free public showing December 2018

Re-staging and performance of a piece developed with Catie Cuan and Catherine Maguire with an audience discussion after produced by Penny Chang.

★ *Twist When Your Ankle Is Out Of Phase*, Parts I, II, and III

Dance Rehearsal Krannert (DRK), Krannert Center for the Performing Arts, Urbana, IL

Free public showing December 2018

Choreographed and performed in an interactive piece as part of original research for a manuscript.

★ *A Machine*.

Evergreen Brick Works, Toronto, ON

ThoughtWorks ParadigmShift October 2018

Choreographed and performed with artist-in-residence Catie Cuan.

★ An installation excerpt of *Time to Compile*

Joe's Pub at the Public Theater, New York, NY

Dance NOW Festival September 2018

Choreographed and performed with artist-in-residence Catie Cuan.

★ "Trio" a shortened excerpt of *Time to Compile*

The Armory Blackbox Theater, Urbana, IL

Studio Exchange Showing July 2018

Developed underlying computational algorithm, choreographed, and performed with Catie Cuan and Catherine Maguire.

★ *Twist When Your Ankle Is Out Of Phase*, Parts I, II, and III

Casa Paganini Infomus, Genoa, Italy

5th Conference on Movement and Computing (MOCO) June 2018

Choreographed and performed with artist-in-residence Catie Cuan and graduate student Ishaan Pakrasi assisted by members of the RAD Lab.

★ *Time to Compile*

The Midway, San Francisco, CA

CODAME Art + Tech Festival June 2018

Choreographed and performed with artist-in-residence Catie Cuan.

★ "Trio" an excerpt of *Time to Compile*

The Ferst Center for the Arts, Georgia Institute of Technology, Atlanta, GA

Arts@Tech SEAD Artists Showcase April 2018

Choreographed and performed with artist-in-residence Catie Cuan assisted by graduate student Ishaan Pakrasi.

★ “Trio” an excerpt of *Time to Compile*

Illinois Program for Research in the Humanities, Urbana, IL

Levis Faculty Center March 2018

Choreographed for performers Erin Berl and Ishaan Pakrasi with Ishaan Pakrasi’s master’s thesis robot design as part of “Marvelous Fabrications: Interrogating Robots from the Middle Ages to the Present.”

★ *Robots in Two Rooms*

The Granoff Center for Creative and Performance Arts, Brown University, Providence, RI

Conference on Research on Choreographic Interfaces (CRCI) March 2018

Week-long residency with artist-in-residence Catie Cuan, graduate student Ishaan Pakrasi, and research technician Erin Berl, presenting a live performance and interactive installation at CRCI 2018. Hosted by Sydney Skybetter.

★ *Time to Compile*

The Ammerman Center for Arts and Technology, Connecticut College, New London, CT

Intersections February 2018

Artist-in-residence Catie Cuan and graduate student Ishaan Pakrasi presented excerpts of in-progress piece.

★ Excerpt from *Time to Compile*

Robotics, Automation, and Dance (RAD) Lab, Urbana, IL

In Progress Showing June 2017

Hosted choreographer Catie Cuan for month of June to collaborate on artistic piece and research exploration with students Ishaan Pakrasi and Novoneel Chakraborty. Advised choreographic and technical development for a piece with interactive and narrative elements. The in progress showing was open to the public and advertised by MechSE Department.

★ *Time to Compile*

In Progress Showing December 2017

Second initial showing of in progress work.

★ *Time to Compile*

Culbreth Theater, University of Virginia, Charlottesville, VA

Fall Dance Concert – University of Virginia November 2014

Worked collaboratively with Dance Program Artistic Director Kim Brooks Mata to facilitate student choreography of a piece which featured live choreography with Dance students as well as motion capture choreography that had been edited by Engineering students.

★ *Integration of Limits*

TOMTOM Festival, Charlottesville, VA

A Score for the Downtown Mall April 2014

Created diagrammatic movement 'score' for dancers and pedestrians to interpret for a performance on the Charlottesville downtown mall as part of the 2014 TOMTOM festival. The score described movement to be performed at the steps by the Charlottesville Transit Center and was part of a larger performance created by Kathryn Schetlick and Veronica Hart.

★ *Untitled Dance Score*

Clough Commons, Georgia Institute of Technology, Atlanta, GA

Automaton April 2013

A contemporary dance performance exploring notions – from academic thesis – of style, robotics, and automated behavior. The performance and related research was featured in an article on the Georgia Tech homepage.

★ I
★ II
★ III
★ IV

Schwartz Center, Emory University, Atlanta, GA

Fieldwork Workshop for Local Artists 2010-2013

★ *Incendiary* Fall 2010
★ *Balance* Spring 2011
★ *The edge of* Summer 2011
★ *Untitled* Fall 2011

The Ferst Center for the Arts, Georgia Institute of Technology, Atlanta GA

So You Think Tech Can Dance?

★ *Reverie* October 2009
★ *Spinning Plates* October 2010

Berlind Theater, Princeton University, Princeton, NJ

Senior Thesis Show *Pleiades* March 2009

★ *Solo* with Francesca Butler, Chang Chan, Whitney Davis, Fletcher Heisler, Lindsey Hornbuckle, Natacha Jamar, Steven Kamara, Zachary Morse, Nikhil Pereira-Kamath, Brandon Racusin, Lara Yuan, Michael Yang
★ *Trio*

Spring Dance Festival February 2008

★ *Fanette* with Laura Robertson

Merce Cunningham Studios, New York, NY

Ivies@Cunningham March 2008

★ *Fanette* with Laura Robertson

Hagan Dance Studio, Princeton University, Princeton, NJ

Select Student Works February 2008

★ *Reverie*

STUDENT THESES
ADVISED WITH
PLACEMENT

- A. Bushman. “Evaluation of Human-like Teleoperated Robot Motion Through Preference, Perception, and Performance-based Studies” *M.S. Thesis, University of Illinois at Urbana-Champaign*. Spring 2020.
★ Associate at a med-tech consulting firm.
- U. Huzaifa. “Control and Hardware Design for a Bipedal Robot Via Planar Modeling with Empirical Perception Studies Leveraging Embodied Movement Analysis.” *Ph.D. Thesis, University of Illinois at Urbana-Champaign*. Fall 2019.
★ Visiting Assistant Professor at Rose-Hulman Institute of Technology.
★ Assistant Professor at DePaul University.
- R. Kaushik. “Developing and Evaluating a Model For Human Motion to Facilitate Low Degree-Of-Freedom Robot Imitation of Human Movement.” *M.S. Thesis, University of Illinois at Urbana-Champaign*. Spring 2019.
★ Accepted to Siemens USA internship and CMU Robotics PhD Program.
- I. Pakrasi. “Towards expressive mobile robots.” *M.S. Thesis, University of Illinois at Urbana-Champaign*. Summer 2018.
★ Accepted technology consulting position at Ernst and Young.
- M. Heimerdinger. “Influence of Environmental Context on Affect Recognition of Stylized Movements.” *M.S. Thesis, University of Illinois at Urbana-Champaign*. Fall 2017.
★ Accepted technology consulting position at Kimley Horn.
- A. Jang Sher. “An Embodied, Platform-invariant Architecture for Robotic Spatial Commands.” *M.S. Thesis, University of Illinois at Urbana-Champaign*. Spring 2017.
★ Accepted program manager position at Microsoft.
- U. Huzaifa. “Movement Theory Inspired Robot Motion Strategies and Design of a Bipedal Walker.” *M.S. Thesis, University of Illinois at Urbana-Champaign*. Summer 2016.
★ Continued to PhD studies at UIUC.
- Y. Sheng “Implementation of a Multiple Switch Time Approach to Style-Based Motion Segmentation.” *M.S. Thesis, University of Virginia*. Fall 2014.
★ Continued to PhD studies at UVA.

KEYNOTE TALKS

RUN CMD

April 2023

Keynote speaker at retreat for Computational Media Design Department of University of Calgary at Barrier Lake Research Station (via Zoom).
Bodies Dancing in Unison: The Illusion of Imitation and Its Impact on Robotics and AI

Annual Meeting of Society for the Neuroscience of Creativity March 2023

Keynote speaker at Society for the Neuroscience of Creativity’s Annual Meeting “Creativity and Artificial Intelligence” at the University of California — San Francisco.
Bodies Dancing in Unison: The Illusion of Imitation and Its Impact on Robotics and AI

Art, Design and Human-Robot Interaction Workshop

May 2022

Keynote speaker for “robo-exoticism”-themed Creative Collaborations workshop co-hosted between Ben-Gurion University and Bezalel Academy of Arts and Design of Jerusalem

Bodies Dancing in Unison: The Illusion of Imitation and Relaxed Notational Abstractions That Capture It

MIG 2020, Clemson, SC October 2020

Keynote speaker at the 13th Annual ACM SIGGRAPH Conference on Motion, Interaction and Games (via Zoom).

Hammers, Paintbrushes, Robots, and Glitter: Embracing Duality in Movement Design and Creating New Tools for Expression with Artist-Engineer Teams

University of California – Berkeley, Berkeley, CA

Art, Technology, and Culture Colloquium January 2020

Dancing With Robots: Expressivity in Natural and Artificial Systems

INVITED TALKS

Cornell University, Online April 2022

Group talk for the Robots and Groups Lab led by Malte Jung.

Bodies Dancing in Unison: The Illusion of Imitation and Relaxed Notational Abstractions That Capture It

HRI 2022 Workshops, Online March 2022

Invited speaker at Workshop On Joint Action, Adaptation, And Entrainment In Human-Robot Interaction

University of Pennsylvania, Philadelphia, PA March 2022

Group talk for Kod*lab, a subsidiary of the GRASP Lab.

Hammers, Paintbrushes, Robots, Ghosts, and Glitter: Embracing Duality in Movement Design and Creating New Tools for Expression with Artist-Engineer Teams

Oregon State University, Online to Corvallis, OR October 2021

Invited speaker for OSU robotics group

Hammers, Paintbrushes, Robots, Ghosts, and Glitter: Embracing Duality in Movement Design and Creating New Tools for Expression with Artist-Engineer Teams

Southern Appalachian Sci. and Eng. Fair, Online September 2021

Invited speaker for high school science and engineering fair participants.

Hammers, Paintbrushes, Robots, and Glitter: Embracing Duality in Movement Design and Creating New Tools for Expression with Artist-Engineer Teams

Rensselaer, Online from Troy, NY March 2021

Invited speaker co-hosted by Curtis R. Priem Experimental Media And Performing Arts Center (EMPAC), Electrical, Computer, and Systems Engineering Department, and the Industrial and Systems Engineering Department.

Hammers, Paintbrushes, Robots, and Glitter: Embracing Duality in Movement Design and Creating New Tools for Expression with Artist-Engineer Teams

Raytheon Technologies, Online September 2020

Invited speaker at the Raytheon Technologies Systems Engineering & Architecture Technology Network Symposium.

Dancing with Robots: Creating Expressive Robotic Systems with Artist-Engineer Teams

ABC Robotics Initiative, Ben-Gurion University [Canceled, Covid-19]

Invited speaker at Agricultural, Biological and Cognitive Robotics (ABC) Robotics Initiative at Ben-Gurion University.

University of Denver, Denver, CO via Zoom

Mechanical and Materials Engineering Department. March 2020
Dancing With Robots: Expressivity in Natural and Artificial Systems

University of Tennessee, Knoxville, TN

Department of Electrical Engineering and Computer Science February 2020
Dancing With Robots: Expressivity in Natural and Artificial Systems

University of California – Berkeley, Berkeley, CA

CITRIS People and Robots Initiative (CPAR) Seminar January 2020
Dancing with Robots: Designing Expression with Machines in Context

University of Illinois at Urbana-Champaign, Champaign, IL November 2019

Department of Psychology
Social-personality-organizational Group Brown Bag Seminar
Prediction of Human Affective Response to Choreographed Motion Stimuli

Workshop on Articulated Actuation Towards Human Capabilities for Robots, Macau, China November 2019

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
Understanding Human-like Movement Through the Lens of Expressivity, Complexity, and Information

University of Illinois at Urbana-Champaign, Urbana, IL

Robotics@UIUC Seminar Series September 13, 2019
Questions About Composition with Natural and Artificial Bodies

Modeling for Robot-assisted and Humanoid Locomotion, New York, NY

Conference, Special Session August 16, 2019
Computer Methods in Biomechanics and Biomedical Engineering (CMBBE)
Toward an Expressive Bipedal Robot: Variable Gait Generation and Validation on a Planar Compass Biped and a Core-Driven Planar Biped Across Multiple Environments

University of California – Davis, Davis, CA

Computer Science & Cinema and Digital Media Seminar May 23, 2019
Dancing With Robots: Expressivity in Natural and Artificial Systems

University of Washington, Seattle, WA

Robotics Colloquium May 17, 2019
Dancing with Robots: Designing Expression with Machines in Context

University of Washington, Seattle, WA

Design. Use. Build. (DUB) Seminar May 15, 2019
Dancing With Robots: Expressivity in Natural and Artificial Systems

The Cooper Union, New York, NY

Mechanical Engineering Departmental Seminar April 23, 2019
Dancing With Robots: Expressivity in Natural and Artificial Systems

- Purdue University**, West Lafayette, IN
 Mechanical Engineering Departmental Seminar February 8, 2019
Dancing With Robots: Expressivity in Natural and Artificial Systems
- Princeton University**, Princeton, NJ
 Mech/Aero Engineering Departmental Seminar November 9, 2018
Dancing With Robots: Expressivity in Natural and Artificial Systems
- Siemens Corporate Technology**, Princeton, NJ
 Seminar November 8, 2018
Robotics, Automation, and Dance (RAD) Lab and AE Machines, Inc
- Beckman Institute, University of Illinois**, Urbana, IL
 Curious and Eclectic Seminar Series November 2, 2018
Dancing With Robots: Expressivity in Natural and Artificial Systems
- Workshop on Humanoid Robot Falling: Fall Detection, Damage Prevention, and Recovery Actions**, Madrid, Spain
 2018 IEEE/RSJ International Conference on Intelligent Robot and Systems (IROS 2018) October 1, 2018
Human Fall Strategies: The Bartenieff Principle of Weight Shift From the Pelvic Core and Its Role in Producing an Expressive Bipedal Walker
- Intrinsically Motivated Artificial Intelligence (IMAI)**, Arlington, VA
 ISAT/DARPA Workshop June 18, 2018
On Expressive Robotic Systems (aka Dancing Robots)
- Midwest Robotics Conference**, Chicago, IL
 Toyota Technological Institute June 15, 2018
On Expressive Robotic Systems (aka Dancing Robots)
- CODAME Art + Tech Festival**, San Francisco, CA
 The Midway June 6, 2018
On Expressive Robotic Systems (aka Dancing Robots) with an Example
 Joint talk with Catie Cuan, Artist-in-residence
- Robots and Art Forum**, Brisbane, Australia
 IEEE Conference on Robotics and Automation (ICRA) May 24, 2018
On Expressive Robotic Systems (aka Dancing Robots)
- Laban Webinar Series**, Zoom Webinar
 Inspirees Institute, LIMS, CAET May 7, 2018
Choreographic Abstractions for Embodied Design of Heterogeneous Robotic Behavior
- Georgia Institute of Technology**, Atlanta, GA
 Georgia Robotics and Intelligent Systems (GRITS) Lab April 19, 2018
On Expressive Robotic Systems (aka Dancing Robots) with an Example
 Joint talk with Catie Cuan, Artist-in-residence
- Distributed, Collective Computation in Biological and Artificial Systems**, Ashburn, VA
 Janelia Research Campus March 19, 2018
On Expressive Robotic Systems (aka Dancing Robots)

- Brown University**, Providence, RI
 Humanities-centered Robotics Initiative March 9, 2018
On Expressive Robotic Systems (aka Dancing Robots) with an Example
 Joint talk with Catie Cuan, Artist-in-residence
- Champaign Public Library**, Champaign, IL
 Tuesdays at Ten Speaker Series September 26, 2017
Choreographic Abstractions for Embodied Design of Heterogeneous Robotic Behavior
- The What Without the How: Specifying Planning Problems in Robotics**,
 Cambridge, MA
 Robotics: Systems and Science (RSS) July 16, 2017
Demonstration as Specification
- Purdue University**, West Lafayette, IN
 Robotics Seminar December 9, 2016
Choreographic Abstractions for Embodied Design of Robotic Behavior
- Workshop on Human Movement Understanding and Robotics**, Daejeon,
 South Korea
 2016 IEEE/RSJ International Conference on Intelligent Robots and Systems
 (IROS 2016) October 14, 2016
Choreographic Abstractions for Embodied Design of Robotic Behavior
- University of Maryland**, College Park, MD
 Brain and Behavior Initiative Seminar April 7, 2016
Choreographic Abstractions for Embodied Design of Robotic Behavior
- Northwestern University**, Evanston, IL
 Master of Science in Robotics Seminar December 1, 2015
Choreographic Abstractions for Embodied Design of Robotic Behavior
- Jefferson County Schools**, New Market, TN
 STEM Enrichment Speaker for Young Girls May 9, 2015
Abstractions for Design-by-Humans of Heterogeneous Robotic Behaviors
- Bard College**, Annandale-On-Hudson, NY
 Computer Science April 30, 2015
Abstractions for Design-by-Humans of Heterogeneous Robotic Behaviors
- University of Illinois at Urbana-Champaign**, Urbana-Champaign, IL
 Department of Mechanical Science and Engineering March 5, 2015
Abstractions for Design-by-Humans of Heterogeneous Robotic Behaviors
- University of Virginia**, Charlottesville, VA
 SWE High School Visitation Weekend February 28, 2015
Abstractions for Design-by-Humans of Heterogeneous Robotic Behaviors
- University of Akron**, Akron, OH
 Integrated Bioscience Seminar Series February 20, 2015
Abstractions for Design-by-Humans of Heterogeneous Robotic Behaviors

- University of Virginia**, Charlottesville, VA
 Design and Data Analysis (DADA) Lecture Series
 Quantitative Psychology Group January 22, 2015
Abstractions for Design-by-Humans of Heterogeneous Autonomous Behaviors
- LAAS-CNRS**, Toulouse, France
 Workshop on Movement Notations and Robot Motions November 13, 2014
Abstractions for Design-by-Humans of Heterogeneous Autonomous Behaviors
- James Madison University**, Harrisonburg, VA
 Society of Women Engineers Seminar October 27, 2014
From Data to Doing: Human-Inspired Autonomous Robotic Systems
- University of Virginia**, Charlottesville, VA
 Society of Women Engineers, Virginia Chapter Conference September 28, 2014
From Data to Doing: Human-Inspired Autonomous Robotic Systems
- Sweet Briar College**, Sweet Briar, VA
 Engineering Department Seminar September 24, 2014
From Data to Doing: Human-Inspired Autonomous Robotic Systems
- University of Virginia**, Charlottesville, VA
 Center for Risk Management of Engineering Systems September 12, 2014
From Data to Doing: Human-Inspired Autonomous Robotic Systems
- University of Illinois at Urbana-Champaign**, Urbana-Champaign, IL
 Decision and Control Seminar September 10, 2014
From Data to Doing: Human-Inspired Autonomous Robotic Systems
- University of Virginia**, Charlottesville, VA
 School of Engineering and Applied Science Open House April 11, 2014
From Dance to Robots: Style-based Abstractions for Human-Inspired Autonomous Systems
- University of Virginia**, Charlottesville, VA
 Wireless Health @ UVA October 4, 2013
From Data to Doing: Human-Inspired Autonomous Robotic Systems
- Emily Carr University**, Vancouver, CAN
 Moving Stories Residency May 22, 2013
Choreographic Abstractions for Robotics
- The Square Room**, Knoxville, TN
 PechaKucha, 20x20 Talk April 25, 2013
Robots and the Arts
- University of Virginia**, Charlottesville, VA
 Systems and Information Engineering Department April 11, 2013
Choreographic Abstractions for Automation, Robotics, the Arts, and Education
- University of Illinois at Chicago**, Chicago, IL
 Department of Electrical and Computer Engineering April 9, 2013
Choreographic Abstractions for Automation, Robotics, the Arts, and Education

- George Mason University**, Fairfax, VA
 Department of Electrical and Computer Engineering April 5, 2013
Choreographic Abstractions for Automation, Robotics, the Arts, and Education
- Clemson University**, Clemson, SC
 Department of Mechanical Engineering March 7, 2013
Choreographic Abstractions for Automation, Robotics, the Arts, and Education
- Rutgers University**, New Brunswick, NJ
 Department of Mechanical and Aerospace Engineering March 4, 2013
Choreographic Abstractions for Automation, Robotics, the Arts, and Education
- University of Memphis**, Memphis, TN
 Department of Electrical and Computer Engineering February 13, 2013
Choreographic Abstractions for Automation, Robotics, the Arts, and Education
- Georgia Institute of Technology**, Atlanta, GA
 NeuroLab January 28, 2013
Choreographic Abstractions for Style-Based Robotic Motion
- Arizona State University**, Tempe, AZ
 School of Arts Media and Engineering January 27, 2012
Style-Based Robotic Motion
- Georgia Institute of Technology**, Atlanta, GA
 Decision and Control Student Symposium April 29, 2011
Automatic Generation of Balletic Motions

INVITED PANELS

- IEEE International Conference on Robotics and Automation**, *Online*
 Sentimental Machines: Celebrating a Decade of Art and Robots at ICRA June 2021
 Invited panelist: Shifting Shapes of Collaboration
- International Foundation for Robotics Research**, *Online*
 Art and Robots September 2020
 Invited panelist for IFRR Robotics Global Colloquia Series.
- College Art Association (CAA) Annual Conference**, Chicago, IL
 ARTificiality: Aesthetics of Embodiment in Digital Art February 2020
Questions About Composition with Natural and Artificial Bodies
- University of Illinois at Urbana-Champaign**, Champaign, IL
 EnterpriseWorks, Research Park November 2019
 Panel: NSF SBIR Workshop Series
- Foundations of Effective Leadership**, Princeton, NJ
 Outdoor Action, Princeton University June 2019
Alumni panel
- Social Media For Scientists: #TweetYourScience**, Urbana, IL
 University of Illinois at Urbana-Champaign November 2018
Expert panel

- 5th Int. Conf. on Movement and Computing (MOCO)**, Genoa, Italy
 Casa Paganini Infomus June 2018
Provocations: What escapes computation in interactive performance?
- Living at the Intersection Symposium**, Princeton, NJ
 Princeton University April 2018
 “Some of the Questions We Ask in The RAD Lab” *Asking Questions organized by Jeff Whetstone and Aynsley Vandenbroucke*
- Marvelous Fabrications**, Urbana, IL
 University of Illinois at Urbana-Champaign March 2018
 “Interrogating Robots from the Middle Ages to the Present” *Panel with ‘Respondent’ Elly Truit, Bryn Mawr College, accompanied by robot demonstrations*
- Conf. for Research on Choreographic Interfaces (CRCI)**, Providence, RI
 Brown University March 2018
 “Working with an Artist-in-Residence in a Robotics Lab”: *Moderated by RPI EMPAC curator Ashley Ferro-Murray.*
 “The Limit Does Not Exist” *Moderated by Christina Wallace and Cate Scott Campbell and also recorded as podcast.*
- Oscillations**, Evanston, IL
 Northwestern University March 2018
Convergence: The future of art, neuroscience and immersive technologies
- Conf. for Research on Choreographic Interfaces (CRCI)**, Providence, RI
 Brown University March 2017
Evening Panel with Featured Participants
- Conf. for Research on Choreographic Interfaces (CRCI)**, Providence, RI
 Brown University March 2016
 “The VR Stack” *Discuss use of virtual reality for crafting robotic movement patterns and testing with humans in NSF ASPIRE project.*
- Princeton Preview: Admitted Students Weekend**, Princeton, NJ
 Princeton University April 2009
 “Senior Thesis Panel”

ORGANIZED
 INVITED/SPECIAL
 ISSUES, SESSIONS,
 AND WORKSHOPS

- A. LaViers, J. Wang, D. Herath, and A. Nilles “Robotics and Art: Automating Expressions” Workshop at IEEE International Conference on Robotics and Automation (ICRA) 2022.
- P. Alves-Oliveira, M. Cakmak, G. Gordon, P. Kahn, A. LaViers, and V. Sarathy. “Creativity and Robots.” Workshop at International Conference on Social Robotics (ICSR) for Special Issue Research Topic with *Frontiers*. 2020.
- N. Fitter, H. Knight, and A. LaViers. “Performing Arts Robots & Technologies, Integrated (PAR-TI).” 4-hour Workshop. *Robotics: Science and Systems (RSS)*. Corvallis, OR via Zoom – Virtual Conference. 2020.
- A. LaViers and C. Cuan. “Merging Artistic and Research Practices Toward More Expressive Robotic Systems.” 5-hour Workshop. *28th IEEE International Conference on Robot & Human Interactive Communication (RO-MAN)*. New Dehli, India. 2019.

- A. LaViers and K. Ozcimder. “Experimenting with Movement Observation.” Half-day Workshop. *Robotics, Science, and Systems (RSS)*. Cambridge, MA. 2017.
- A. LaViers. “Embodied Experience and Movement Observation for Roboticists.” Half-day Workshop. *Robotics, Science, and Systems (RSS)*. Ann Arbor, MI. 2016.
- A. LaViers and N. Leonard. “Controls and Art.” Invited Session. *American Control Conference (ACC)*. Montreal, CAN. 2012.
- N. Leonard, A. LaViers, and S. Marshall. “Feedback, interaction and movement in human groups: A participatory event.” Special Session. *American Control Conference (ACC)*. Montreal, CAN. 2012.
- A. LaViers and M. Egerstedt. Invited Session: “Controls and Art.” *American Control Conference (ACC)*. San Francisco, CA. 2011.

CURATION AND
PRODUCTION

Robotics and Art at 319 May 2022
Co-organized with Diedra Krieger a month-long series of shows of robotic art at Philadelphia-based art galleries sponsored by the RAD Lab and ICRA ‘22. Guest-curated “Deflating Heroics” by Kate Ladenheim for the atrium space.

WORKSHOPS AND
SYMPOSIA

Camp LBMS June 2023
Presentation with Cat Maguire at the Laban/Bartenieff Institute of Movement Studies online event.
Outlining the Time Component and Establishing the BESST System

BGU Design Workshop May 2022
Robotics and dance workshop for interdisciplinary group, focused on design. [Canceled.]
Let’s Move, Notate, and Create Together: Using Our Innate Imitation Abilities to Explore What Robots Can Express

HRI 2022. Online March 2022
Accepted paper at HRI in Public Spaces Workshop.
“The Use of Breath in a Public Robotic Art Installation: Movement Analysis Reveals Rich Kinesthetic Exchange Between Human and Robot” by K. Ladenheim, A. LaViers, and C. Maguire.

Robotics x Arts Exhibition: Opportunities and Issues in Robotics Applied in the Arts. Online
Robotics, Science, and Systems (RSS) July 2021
Invited artist presenter

Artificial Intelligence in Digital Culture. Tempe, AZ
Arizona State University August 2020
Invited expert advising the School of Arts, Media and Engineering at a half-day virtual conference on incorporating AI into the humanities

Conference for Research on Choreographic Interfaces (CRCI). Providence, RI
Brown University. March 2020
Featured participant, on panel discussing *Babyface* with Kate Ladenheim

ORD Camp, Chicago, IL

Google Headquarters – Chicago
Invited interdisciplinary “unconference”
Presented a session on “Movement Notation”

January 2020

Affect Modeling, Evaluation, and Challenges in Intelligent Cars. Macau, China

2019 IEEE/RSJ International Conference on Intelligent Robots and Systems
(IROS 2019)
Presenting concept “Using Affective Measurements of Pedestrian Gait to Improve
Autonomous Vehicle Performance in Mixed Driver Settings” co-authored with
Katherine Driggs-Campbell. (to appear)

November 2019

Microsoft Technology Center, Grand re-opening, Chicago, IL

Aon Center, downtown Chicago
Presented an art installation that included a Kinect-powered photobooth (a caali,
LLC prototype) at MTC Chicago grand-reopening.

October 2019

DreamWakers Strategy Summit, Washington, DC

DreamWakersHQ
Invited participant at the first strategy summit for online-education/edtech non-
profit DreamWakers.

October 2019

Workshop on Teleoperation of Humanoid Robots. Toronto, Canada

2019 IEEE-RAS International Conference on Humanoid Robots (Humanoids
2019)
Paper presentation: “Generating Human-Like Motion on Robots Through Tele-
operation in Functional Tasks” A. Bushman, M. Asselmeier, J. Won, and A.
LaViers.

November 2019

US Robotics Roadmap Workshop. Chicago, IL

UIUC Illini Center
Updating the US robotics roadmap, by invitation only, selection on the basis of
1.5 page whitepaper. Workshop led by Nancy Amato.

September 2019

RAD Lab Technology Playground. Cleveland, OH

DanceUSA Conference.
An invited, extended hands-on session with new and emerging technologies that
are intersecting with movement and dance work, including virtual reality, motion
capture, robots and more in concert, site-specific, and screen dance. This event
is designed to share the experience of working with emerging technology and how
such investigation can inform artistic practice.

June 2019

Greetings/Goodbyes Workshop, Seattle, WA

University of Washington
Embodied Movement Workshop co-led with Elin Bjorling
Project EMAR at the University of Washington

May 2019

Symposium on “Movement that Shapes Behaviour” Falmouth, UK

Artificial Intelligence and Simulation of Behaviour (AISB) 2019
Extended abstract: R. Kaushik and A. LaViers, “Using verticality to classify
motion: analysis of two Indian classical dance styles.”

March 2019

Conference for Research on Choreographic Interfaces (CRCI). Providence, RI

Brown University.
Invited participant.

February 2019

Modeling And Control Of Dynamic Legged Locomotion: Insights From Template (Simplified) Models, Madrid, Spain

2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2018) October 1, 2018

Paper, presentation, poster: “An Embodied Movement Inspired Bipedal Robot Design with Core-Located Actuation” U. Huzaifa, C. Maguire, and A. LaViers.

Assistance and Service Robotics in a Human Environment, Madrid, Spain

2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2018) October 1, 2018

Paper, presentation: “An Expressive Layer for Mobile Robots” I. Pakrasi and A. LaViers.

TED, New York, NY

TED Headquarters May 31, 2018

Attendee at live TED Residency Talks, featuring RAD Lab Artist-in-residence and TED Resident, Catie Cuan

Robots and Art Forum, Brisbane, Australia

IEEE Conference on Robotics and Automation (ICRA) May 24, 2018

Paper, presentation: “Time to Compile: Compliance Between Artistic Inquiry and Research Questions” C. Cuan and A. LaViers.

Conference for Research on Choreographic Interfaces (CRCI). Providence, RI

Brown University. March 2018

Featured participant for two panels and showing of in-progress work.

Creativity Workshop, Urbana, IL

Gies College of Business, UIUC December 14, 2017

Participant

Minimality and Trade-offs in Automated Robot Design, Cambridge, MA

Robotics: Science and Systems (RSS) July 16, 2017

Comment, presentation: “Expressivity: Form vs. Function”

Conference for Research on Choreographic Interfaces (CRCI). Providence, RI

Brown University. March 2017

Invited Participant for an evening panel.

Led breakout discussion: “Arts and Money” *Brainstorm various approaches to making money and financing artistic projects (contrasting to technical projects)*.

Combining Optimal Control, Reinforcement Learning and Movement Primitives to Achieve Better Robot Motions, San Francisco, CA

IEEE International Conference on Simulation, Modeling, and Programming for Autonomous Robots (SIMPAN) December 13, 2016

Poster: “Patterns of Body Organization Implemented for a 4-limb robot” U. Huzaifa, A. LaViers

Humans, Machines, and the Future of Work, Houston, TX

De Lange Conference X December 5, 2016

Poster: “Function and Expression Within Recipe” A. LaViers, K. Bradley

Workshop on Artistically Skilled Robots, Daejeon, South Korea

2016 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2016) October 14, 2016

Paper, poster: “Design of perceptually meaningful quality in robotic motion” L. Bai, J. Bellona, L. Dahl, and A. LaViers.

Human Movement Understanding and Robotics, Daejeon, South Korea

2016 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2016) October 14, 2016

Presentation: “A platform-invariant architecture for high-level spatial robotic commands” A. Jang Sher, U. Huzaifa, V. Jain, J. Li, A. LaViers

Workshop on Automation Supporting the Elderly, Daejeon, South Korea

2016 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2016) October 9, 2016

Presentation: “Laban-Inspired Task-Constrained Expressive Motion Generation for UAVs Supporting Elderly Independent Residence” H. Cui, C. Maguire, A. LaViers

Conference for Research on Choreographic Interfaces (CRCI). Brown University. March 2016.

Invited Participant for a panel and dinner.

The VA Academy of Science, Eng., and Medicine (VASEM). Washington D.C.

National Academy of Science December 2014

The Virginia Summit on Science, Engineering, and Medicine: Big Data

Poster: “Somatic Theory and High-level Robotic Control: Ongoing work in the Robotics, Automation, and Dance (RAD) Lab.” A. LaViers

5th *Workshop on Formal Methods for Robotics and Automation*. Berkeley, CA

Robotics and Science Systems (RSS) June 2014

Poster: “Towards Verified Planar Formation Control Algorithms by Composition of Primitives.” L. Bobadilla, T. T. Johnson, A. LaViers

2nd *NSF Wkshp on Formal Composition of Motion Primitives*. Philadelphia, PA

CPS Week. May 2013

Paper, presentation: “Stylistic Sequencing: Choreographic Abstractions for Robotic Motion Planning.” A. LaViers and M. Egerstedt

PRESS

O. Whang. “This Robot Can Paint. But Is It Art?” *The New York Times*. May 2, 2023.

C. Cuan. “Dances with Robots: Choreographing, Correcting, and Performing with Moving Machines.” *The Drama Review (TDR)*, Volume 65, Issue 1, pp. 124 - 143. Cambridge University Press. March 18, 2021.

S. Skybetter. “How Choreography Can Help Robots Come Alive” *Wired*. February 7, 2021.

N. Loeffler-Gladstone. “The New Museum’s NEW INC’s EdgeCut Performance Series Curated by Heidi Boisvert and Kat Mustatea.” *The Dance Enthusiast*. December 1, 2020.

G. Curtis. “Dances With Robots, and Other Tales From the Outer Limits.” *The New York Times*. November 5, 2020.

- R. Latanision, C. Fletcher, and A. LaViers. “An Interview with...” *The Bridge*. National Academy of Engineering. March 20, 2020.
- S. Skybetter. “What Are the Potential Military Applications of Teaching Robots to Dance?” *Dance Magazine*. February 17, 2020.
- S. Woods. “Q&A: How can the tech world leverage dancers’ creativity?” *Dance Magazine*. January 8, 2020.
- M. Holloway. “RAD Lab, artist-in-residence collaborate to combine art and science.” *Grainger College of Engineering*. August 8, 2019.
- Julie Rose (live interview). “Top of Mind,” *Brigham Young University (BYU) Radio*. February 28, 2019.
- T. Tucker, MechSE Communications. “LaViers argues for more human-like robotic motion” *Department of Mechanical Science and Engineering*. February 26, 2019.
- J. Goodrich. “Amy LaViers, a Mechanical Engineer Working in the Arts: How she’s using her STEAM education to help improve robots used by DARPA” IEEE Member Profile, *The Institute: The IEEE News Source*. January 14, 2019.
- E. Innes. “How Tweet It Is! I-MRSEC Workshop Helps Scientists Incorporate Twitter into Their Scientific Communication Repertoire” *I-Stem Education Initiative*. November 20, 2018.
- A. Herman. “ARTOBOTS: CODAME’s Art + Tech Festival @ The Midway”. *State of the Art*. July 6, 2018.
- I. Malatesta. “Our Changing Relationship With Robots.” *Medium* for CODAME Arts+Tech Festival. April 24, 2018.
- A. Morris. “Meet Amy LaViers: The Choreographer Engineer Teaching Robots To Dance For DARPA” *Forbes*. April 4, 2018.
- C. Wallace and C. Scott Campbell “The Limit Does Not Exist in ChoreoTech”: *Forbes*. March 19, 2018.
- E. Innes. “Mattia Gazzola’s Paper2Tree: A 3-Step Program to Give Back to Your Community: Publish a Paper; Plant a Tree; Perform a School Outreach” *I-Stem Education Initiative*. December 1, 2017.
- MechSE Communications. “LaViers steps up research on robotic choreography with extended DARPA award” *Department of Mechanical Science and Engineering*. June 13, 2017.
- E. Innes. “LaViers’ RAD Lab Uses Robots/Dance to Study Movement, Provide Automation”. *I-Stem Education Initiative*. September 8, 2016.
- E. Scott. “Using dance to design robotics control systems.” *The Daily Illini*. March 28, 2016.
- MechSE Communications. “DARPA research uses human movement concepts to improve robotic control systems.” *Department of Mechanical Science and Engineering*. January 12, 2016.
- J. Markoff. “As Aging Population Grows, So Do Robotic Health Aides.” *The New York Times*. December 4, 2015.

- C. Oehler, MechSE Communications. “Passion for dance moves new professor toward improved control systems.” *Department of Mechanical Science and Engineering*. November 17, 2015.
- A. Bisbort. “Do the Robot.” *UVA Alumni Magazine*. Fall 2014.
- M. Jaffee. “Passion for Dance and Engineering Leads Amy LaViers into Robotics Research.” *UVA Today*. June 9, 2014.
- L. Klipp. “Boogie Bots.” *Georgia Tech Alumni Magazine*. Vol. 89, No. 03. 2013.
- T. Riordan. “Learning the Primary Colors of Dance.” *EQN*. Princeton University School of Engineering and Applied Science blog. June 4, 2009.

HONORS

- IEEE Robotics and Automation Letters**, London, UK May 2023
- ◇ *Outstanding Associate Editor*
 - ★ Outstanding Associate Editor for the IEEE Robotics and Automation Letters – announced at the IEEE International Conference on Robotics and Automation (ICRA) 2023 Award Ceremony.
- The Robot of the Year Awards, Station F**, Paris, France November 2018
- ◇ *Robot of the Year, Finalist*
 - ★ One of twelve finalists (AE Machines) for an honor centered around ethical innovation in robotics and AI.
- Princeton University**, Princeton, New Jersey November 2018
- ◇ *Student Selected Speaker*
 - ★ Inaugural student-selected departmental speaker in the Mechanical and Aerospace Engineering Department.
- 4th Revolution Awards**, Chicago, IL October 2017
- ◇ *Product Design of the Year*
 - ★ Selected for contributions to manufacturing innovation through the AE Design Tool by AE Machines, Inc. Honored in a photograph with the governor of Illinois.
- Defense Advanced Research Projects Agency**, Arlington, VA October 2017
- ◇ *Director’s Fellowship 2017*
 - ★ DARPA YFA Grant, entitled *Choreography of Embodied, Platform-invariant Motion Primitives*, was extended for 3rd year of funding after a competitive selection process.
- University of Illinois at Urbana-Champaign**, Urbana, IL Spring 2017
- ◇ *List of Teachers Ranked as Excellent By Their Students, Outstanding Distinction*
 - ★ Ranked in top 10% across evaluation criteria.
- University of Illinois at Urbana-Champaign**, Urbana, IL Spring 2016
- ◇ *University Nominee for Packard Fellowship*
 - ★ Selected by Vice Chancellor for Research, Peter Schiffer, and a faculty review committee to submit a full proposal to the Packard Foundation for a Packard Fellowship in Science and Engineering.

Defense Advanced Research Projects Agency, Arlington, VA October 2017

◇ *Young Faculty Award 2015*

- ★ Recipient of DARPA YFA Grant, entitled *Choreography of Embodied, Platform-invariant Motion Primitives*.

Georgia Institute of Technology, Atlanta, GA May 2013

◇ *CETL/BP Outstanding Graduate Teaching Assistant Award Finalist*
Institute-wide

- ★ Finalist for the only institute-wide award for graduate teaching presented by the Center for Education, Teaching, and Learning (CETL) and BP.

◇ *ECE Graduate Teaching Excellence Award*
School of Electrical and Computer Engineering

- ★ Awarded to recognize excellence in graduate teaching in the School of Electrical and Computer Engineering.

Princeton University, Princeton, NJ June 2009

◇ *John Marshall Funding Prize*
School of Engineering and Applied Science

- ★ The award, which required a funding proposal prior to completion of the project, provided significant additional funding to undergraduate senior thesis, “Learning the Primary Colors of Dance.”

◇ *Calvin Dodd MacCracken Senior Thesis Prize*
School of Engineering and Applied Science

- ★ Awarded to undergraduate thesis “Learning the Primary Colors of Dance.” The award recognized the top three senior theses in the School of Engineering and Applied Sciences.

◇ *Morgan Mckenzie Senior Thesis Prize*
Department of Mechanical and Aerospace Engineering

- ★ Awarded to undergraduate thesis “Learning the Primary Colors of Dance.” The award recognized the top senior theses in the Department of Mechanical and Aerospace Engineering.

◇ *Lyman Page Dance Award*
Lewis Center for the Arts

- ★ Awarded for outstanding use of dance in undergraduate thesis “Learning the Primary Colors of Dance.”

Jet Propulsion Laboratory, Pasadena, CA August 2008

◇ *JPL Spot Award*
High Contrast Imaging Testbed

- ★ For “outstanding performance and lasting contribution” in the role of helping to align an optical testbed for phase-induced amplitude apodization (PIAA).

FUNDED PROJECTS
\$1,669,622 TO PI
OF \$4,320,436

An Open Data Infrastructure for Bodily Expressed Emotion Understanding

National Science Foundation (NSF)

CISE CCRI Community Research Infrastructure

April 2023-April 2026 \$1,832,335 RAD Lab share via subaward through Penn State: \$463,413

Understanding Movement Style and Social Interactions Through Participatory Performance

Institute For Research in the Humanities (IPRH), University of Illinois at Urbana-Champaign

Research Cluster

May 2019-May 2020 \$2,500 Co-PI share: ~\$1,250

Taskable, Adaptive, and Human-Sensitive Autonomous Systems for Energy-Efficient and Comfortable Buildings

Institute For Sustainability, Energy, And Environment (iSEE), University of Illinois at Urbana-Champaign

“Campus as a Living Laboratory” Seed Funding Program

March 2019-August 2019 \$30,000 Co-PI share: ~\$15,000

I-Corps: Context-Aware Interactive Robotics

National Science Foundation (NSF)

Innovation Corps

July 2018-June 2019 \$50,000

EAGER: Center-of-Mass Control for Expressive and Effective Movement in Bipedal Robots

National Science Foundation (NSF)

CMMI

August 2017-July 2018 \$136,524 Lead PI share: \$71,111

I-Corps: AE Machines: Easy-to-Use Software for Automation

National Science Foundation (NSF)

Innovation Corps

January 2016-December 2016 \$50,000

Choreography of Embodied, Platform-invariant Motion Primitives

Defense Advanced Research Projects Agency (DARPA)

Young Faculty Award (YFA) 2015

Director’s Fellowship 2017

December 2015-December 2018 \$630,708

NRI: Collaborative Research: ASPIRE: Automation Supporting Prolonged Independent Residence for the Elderly

National Science Foundation (NSF)

National Robotics Initiative (NRI)

August 2015-August 2018 ~\$1,295,917 Co-PI share: \$239,734

Data-driven Design of Movement and Sound

UVA Data Science Institute Presidential Fellowship

September 2015-September 2016 ~\$60,000 in form of two student fellowships PI Share: one fellowship

Nucleus Fellowship

University of Virginia

September 2014-May 2015 \$10,000

Methodologies for Real, Time Diagnostics and Prognostics and For Cyber-Security in Smart Manufacturing Systems

National Institute of Standards and Technology (NIST)

September 2014-May 2015 \$150,000 Co-PI Share: \$50,000

Dual-Arm Robot Advantages

Commonwealth Center for Advanced Manufacturing (CCAM)

May 2014-December 2014 \$49,157

Quantitative Arts at UVA: Electronic Identity and Embodied Technology Atelier

The Jefferson Trust

May 2014-April 2015 \$22,295 Lead PI Share: \$8,249

Educational Diversity Fellowship (EDF)

University of Virginia

August 2013-August 2014 \$1,000

INDUSTRY
EXPERIENCE

Soma Measure, Inc, Philadelphia, PA

Co-founder and CEO/CTO

2020 - 2021

Wearable technology for breath-sensing.

CAAIL, LLC, Champaign-Urbana, IL

Co-founder and CCO/CTO

2018 - 2020

Developing offline, embodied experiences that connect participants to their digital devices and lived experiences.

- * Received NSF Innovation Corps \$50,000 award and participated in 7 week customer discovery intensive.
- * Embodied photobooth vendor at ArtShow Chicago Fashion Show 2; hosted 38 participants in 1 hour.
- * Embodied photobooth installation at The Video Game Art (VGA) Gallery, Chicago, IL.
- * Installed permanent Kinect-powered embodied photobooth for Microsoft Technology Center (MTC) – Chicago, which is being featured at the October 2019 grand re-opening. The installation will have the possibility to be networked to nodes at other MTCs around the world.

AE Machines, Inc, Champaign-Urbana, IL

Co-founder and CTO

2015 - 2019

Leading technical development of prototype software for highly-abstracted automation software.

- * Accepted to University of Illinois Research Park EnterpriseWorks Incubator.
- * Received NSF Innovation Corps \$50,000 award and participated in 7 week customer discovery intensive.
- * Received NSF SBIR Phase I \$225,000 grant to demonstrate feasibility of an accessible approach to factory automation.
- * Completed 10 week Y Combinator Start Up School course (SUS17).
- * Received letters of support from two regional manufacturers and two venture investors for follow on funding.
- * Honored at inaugural 4th Revolution Awards in Chicago, IL, winning memberships to the Digital Manufacturing and Design Innovation Institute (DMDII) and mHUB.
- * One of 12 finalists at inaugural Robot of the Year Awards in Paris, France.
- * Visited *World of Concrete 2020* as an automation consultant for 2X Hydro-demolition, Las Vegas, NV.

TEACHING
EXPERIENCE

Princeton University Princeton, NJ

Guest Artist

Spring 2023

STC/EGR/MUS 209: Transformations in Engineering and the Arts

- ★ Guest artist for 2-week “movement module.”
- ★ Developed in-class activities surrounding notation, translation, choreography, somatics, and robotics.
- ★ Lectured on research and artistic practice.

Barnard College at Columbia University New York, NY

Guest Artist

Fall 2021

COMS3997 New Directions in Computing: Arts and Computing in NYC

- ★ Guest artist, with Kate Ladenheim, for 2-weeks on “Robotics, Wearables, and Dance” of cross-institution course with computer science students at Barnard and fashion design students at Fashion Institute of Technology (FIT).
- ★ Developed in-class activities surrounding prototyping, movement research, and design.
- ★ Lectured on research and artistic practice for piece *Babyface*.

Princeton University Princeton, NJ

Guest Artist

Spring 2021

STC/EGR/MUS 209: Transformations in Engineering and the Arts

- ★ Guest artist for 2-week “movement module.”
- ★ Developed in-class activities surrounding notation, translation, choreography, somatics, and robotics.
- ★ Lectured on research and artistic practice.

University of Illinois Urbana-Champaign, IL

Assistant Professor

Fall 2015- Summer 2020

RAD Lab Summer Internship (remote) *Summer 2020*

- ★ Developed remote independent study framework for 4 undergraduate students.

ME 340 Dynamics of Mechanical Systems *Spring 2020*

- ★ Presents system notation, Euler-Lagrange equations, stability, and other foundational concepts in systems theory.
- ★ Deployed online learning frameworks to accommodate remote communication in light of COVID-19.

ECE 470 Introduction to Robotics *Fall 2019*

- ★ Guest lecture for Prof. Katie Driggs-Campbell.

ARCH 593 Design and Construction Futures *Fall 2019*

- ★ Guest lecture for Prof. Tait Johnson Architecture Department graduate course, tour of the RAD Lab, and will provide feedback on upcoming project designs.

FAA 110 Exploring Arts and Creativity *Fall 2019*

- ★ Co-teaching freshman seminar on creativity with Music Department faculty Prof. Gabriel Solis.
- ★ Class is taught on a by-invitation basis, bringing together faculty from across campus to show freshman that creativity is a thread that exists across disciplines.

ME 340 Dynamics of Mechanical Systems *Fall 2019*

- ★ Presents system notation, Euler-Lagrange equations, stability, and other foundational concepts in systems theory.
 - ★ Deployed an open-ended revision of the course homeworks.
- ME 470 Senior Design *Fall 2019*
- ★ Advised team of seniors in a design project for Beckman Institute MRI researcher, Justin Rhodes.
 - ★ The team is developing an augmentation device and exercise program for MRI machine that holds a participants head still while performing vigorous exercises with the lower body.
- DANCE 366 Dance Composition *Spring 2019*
- ★ Guest artist at University of Washington.
- DANCE 251 The Creative Process *Spring 2019*
- ★ Guest artist at University of Washington.
- DAN 245 Introduction to Somatics *Spring 2019*
- ★ Guest lecture for Prof. Rebecca Nettle-Fiol, Dance Department.
- ARCH 593 Design and Construction Futures *Spring 2019*
- ★ Guest lecture for Prof. Tait Johnson Architecture Department graduate course.
- ME 598 Movement Representation + High-level Robotic Control *Spring 2017*
- ★ Seminar oriented around movement notation, dance, supervisory control, multi-agent control, and optimal control in the context of robotics.
 - ★ Emphasized written work.
- FAA 110 Exploring Arts and Creativity *Fall 2018*
- ★ Co-taught freshman seminar on creativity with Dance Department faculty Prof. John Toenjes.
 - ★ Established a framework for developing an ongoing creativity in freshmen through daily creative practice.
 - ★ Facilitated discussion of weekly artistic performances and events that the class attended in addition to class meeting.
 - ★ Class is taught on a by-invitation basis, bringing together faculty from across campus to show freshman that creativity is a thread that exists across disciplines.
- ME 498 Bio-inspired Design *Spring 2018*
- ★ Panel on bio-inspired robotics.
 - ★ Filmed interview available at:
https://mediaspace.illinois.edu/media/t/1_cq1znrzg
- ME 340 Dynamics of Mechanical Systems *Spring 2017*
- ★ Presents system notation, Euler-Lagrange equations, stability, and other foundational concepts in systems theory.
 - ★ Emphasized written description of systems and technical concepts.
 - ★ Incorporated embodied movement analysis activity.
- TAM 195 Mechanics in the Modern World *Fall 2017*
- ★ Guest lecture on research.
- ME 340 Dynamics of Mechanical Systems *Fall 2017*
- ★ Presents system notation, Euler-Lagrange equations, stability, and other foundational concepts in systems theory.
 - ★ Emphasized written description of systems and technical concepts.
- ME 470 Senior Design *Fall 2017*
- ★ Advised team of seniors in a design project for start up Pysonic, Inc.
 - ★ The team conducted stress-tests on and made design improvements to components for a low-cost prosthetic hand.
- ME 497 Independent Study *Fall 2017*
- ★ Led independent study course for three undergraduate students. Each student develops own project through guided research and readings, makes midterm

- project proposal, and completes project in a final write up and presentation.
(3 students enrolled.)
- ME 498 Bio-inspired Design *Spring 2017*
 ★ Guest lecture on bio-inspired robotic walking.
- ME 497 Independent Study *Spring 2017*
 ★ Led independent study course for three undergraduate students. Each student develops own project through guided research and readings, makes midterm project proposal, and completes project in a final write up and presentation.
(3 students enrolled.)
- ME 598 Movement Representation + High-level Robotic Control *Spring 2017*
 ★ Seminar oriented around movement notation, dance, supervisory control, multi-agent control, and optimal control in the context of robotics.
 ★ Emphasized written work.
- ME 470 Senior Design *Fall 2016*
 ★ Advised team of seniors in a design project for start up AE Machines, LLC.
 ★ The team created modular arduino code that corresponded to 3-D printable parts for easy-to-use automation cell design.
- TAM 195 Mechanics in the Modern World *Fall 2016*
 ★ Guest lecture on research.
- ME 340 Dynamics of Mechanical Systems *Fall 2016*
 ★ Presents system notation, Euler-Lagrange equations, stability, and other foundational concepts in systems theory.
 ★ Emphasized written description of systems and technical concepts.
- ME 540 / ECE 515 Control System Theory and Design *Spring 2016*
 ★ Presents mathematically concise representations of notions like feedback, controllability, observability, and stability for a narrow class of systems.
 ★ Developed system of in-class worksheets to facilitate active learning.
- ME 497 Independent Study *Spring 2016*
 ★ Led independent study course for three undergraduate students. Each student develops own project through guided research and readings, makes midterm project proposal, and completes project in a final write up and presentation.
(3 students enrolled.)
- CS 598RK Graduate Seminar *Fall 2015*
 ★ Guest lecture for Prof. Ranjitha Kumar Computer Science Department graduate course.
- KIN 257 Coordination, Control, and Skill *Fall 2015*
 ★ Guest lecture for Prof. Citlali Lopez-Ortiz in Kinesiology.

University of Virginia Charlottesville, VA

Assistant Professor

Fall 2013-Spring 2015

- ARAD 5500 Introduction to Design Thinking *Fall 2014*
 ★ Guest lecture for School of Architecture course on design. Led embodied exercises and related them to movement representation and control of autonomous systems. The lesson employed exercises in movement and writing and was informed by Bartenieff Fundamentals, motion capture technology, and finite state machines.
- 4th year Capstone *Fall 2014 - Spring 2015*
 ★ Facilitated students in a funded project developing a robotic therapy system for the UVA Children's Hospital.
- SYS 6012 / MAE 6620 / ECE 6852: Linear Systems *Fall 2014-present*
 ★ Taught interdisciplinary course as a stand-alone introduction to control theory that covered results on stability, controllability, and observability for state-space linear systems and control design using pole-placement and linear-

quadratic regulators with emphasis on mathematical rigor coupled with qualitative description and observation.

DANC 3559 / ENGR 3501 Electronic Identity and Embodied Technology Atelier (new course) *Fall 2014*

- ★ Proposed course to The Jefferson Trust for necessary funding.
- ★ Initiated collaboration with Kim Brooks Mata, artistic director of UVA's dance program, to produce this new, interdisciplinary course.

SYS 2202 Data and Information Engineering *Spring 2014-present*

- ★ Designed a course-long project where students developed a web-based remotely hosted relational database via weekly homework assignments.
- ★ Created guest lecture series featuring professionals who had worked with data engineering in four diverse fields: healthcare, finance, consumer products, and big data.
- ★ Developed final paper assignment for students to explore a key, emerging area of data engineering.

4th year Capstone for Technology Leaders Program (co-advised) *Fall 2013 - Spring 2014*

- ★ Facilitated students as they integrated many subsystems to create an automated cell culturing system in Dr. Robin Felder's lab.

Coursera, Massively Open, On-line Course (MOOC)

Teaching Assistant

Fall 2012-Spring 2013

Teaching Assistant for "Control of Mobile Robots" course.

- ★ Created weekly "Glue Lectures" to prepare students for the weekly quizzes which comprised the course. These lectures reiterated important concepts from that week and presented detailed examples for the students to reinforce the weekly learning objectives.
- ★ Developed reference tracking example using a humanoid robot, demonstrating concepts in controllability, observability, and stability.
- ★ This on-line course was used for a flipped classroom course in the spring that will use short video tape segments to supplement in-class hands on robotic experiments. At the conclusion of the first run of this course, which occurred in the winter of 2013, 3,295 students had completed the requirements for passing the course.

Georgia Institute of Technology, Atlanta, GA

Graduate Teaching Assistant

Fall 2012

Co-taught ECE 3084: Signals and Systems, a brand new course aimed at showing students the connections between signal analysis and control systems.

- ★ Prioritized syllabus objectives, emphasizing the inclusion of big picture break-aways even during introductory lectures.
- ★ Developed and coordinated hands-on in-class labs designed to demonstrate theoretical concepts in action.
- ★ Presided over lectures, wrote code to demonstrate key concepts, and guided students through concepts during office hours.
- ★ Improved homework and exam questions, reconciling assessment goals with actual student perspective.

Teaching Assistant

Spring 2012

Teaching Assistant for ECE 3085: Introduction to Systems and Controls.

- ★ Coordinated in-class programming assignments for go-to-goal and obstacle avoidance tasks using Khepera robots.

- ★ Coached teams of students through concepts in PID control and behavior based robotics, enabling them to successfully complete a programming challenge.

Graduate Teaching Assistant Fall 2011

Teaching Assistant for ECE 6550: Linear Systems, the introductory control course for 150 graduate students.

- ★ Administered lectures and coached students through difficult concepts in weekly office hours.
- ★ Aided in homework and exam development.

Head Teaching Assistant Summer 2010

Head Teaching Assistant for Hands-On-Tech (HOT Days) summer program for high school students.

- ★ Coordinated all teaching assistants for the summer program.
- ★ Oversaw high school students as they learned college-level concepts through a series of interactive and hands-on labs designed to attract students to GA Tech and STEM fields.

Duke University, Durham, NC

Teaching Assistant Summer 2007

Teaching Assistant for Duke Talent Identification Program (TIP) summer course on Aerospace Engineering.

- ★ Supervised high school students in a boarding school setting.
- ★ Overcame difficult staffing situation as the professor for the course was fired midterm. Stepped into much larger instructive role in the interim.
- ★ Integrated spending time outdoors with hands-on experiments like the demonstration of a Pitot tube in Duke's famous garden streams.

RESEARCH
EXPERIENCE

The Robotics, Automation, and Dance (RAD) Lab, Philadelphia, PA

Director Summer 2013 - present

Director of the Robotics, Automation, and Dance (RAD) Lab, which established as an independent organization in 2020.

University of Illinois, Urbana, IL

Faculty Position Fall 2015 - Summer 2020

Director of the Robotics, Automation, and Dance (RAD) Lab

University of Virginia, Charlottesville, VA

Faculty Position Fall 2013 - Spring 2015

Director of the Robotics, Automation, and Dance (RAD) Lab

Georgia Institute of Technology, Atlanta, GA

Graduate Research Assistant Fall 2009 - Spring 2013

Research Assistant in the Georgia Robotics and Intelligent Systems (GRITS) Lab.

- ★ Coordinated and oversaw use of VICON motion capture system.
- ★ Systematized use of NAO Aldebaran Humanoid robot platform.

Jet Propulsion Laboratory (JPL), Pasadena, CA

Research Technician

Summer 2008

Research technician in the High Contrast Imaging Testbed (HCIT).

- ★ Aligned optical elements to help create a testbed for phase-induced amplitude apodization (PIAA), a proposed telescope configuration for detecting extrasolar Earth-like planets, and began a project to analyze the sensitive temperature control issues associated with the high precision alignment.

Princeton University, Princeton, NJ

Research Intern

Summer 2006

Boeing-sponsored intern in research lab in Mechanical and Aerospace Engineering Department.

- ★ Programmed a user interface in LabVIEW to control of a prototype deformable mirror for NASA's Terrestrial Planet Finder (TPF) mission.

UNIVERSITY
SERVICE

University of Illinois, Urbana, IL

Robotics@UIUC Seminar Series

2019

- ★ Organized and coordinated robotics seminar series to build inertia around robotics on campus with John Hart and Saurabh Gupta.

Undergraduate Programs Committee

2015-2019

- ★ Member
- ★ Subcommittee to review 400 and 500 level courses; Spring 2016.
- ★ Subcommittee on ICES evaluations; Fall 2017.
- ★ ABET Certification – Institutional Criterion 8; Spring 2019.

Strategic Planning Activity

December 7, 2017

- ★ Participated in Goal I: *Foster scholarship, discovery and innovation*

University of Virginia, Charlottesville, VA

Internal Operating Board (IOB)

Commonwealth Center for Advanced Manufacturing (CCAM)

Fall 2014

- ★ Sat in for UVA representative for bi-annual operations meeting of CCAM.
- ★ Served as Secretary, taking notes and distributing to the rest of the industry/university board after the meeting.

Departmental Space Committee

2014-2015

- ★ Newly formed committee to coordinate the use of space in the department.

Nucleus Fellowship

2014-2015

- ★ Completed overhaul of SYS 2202 Data and Information Engineering course in year-long fellowship.
- ★ Participated in UVA's Course Design Institute, Summer 2014.

Departmental Search Committee

Summer 2014

- ★ Served on search committee for a three-year lecturer position in the topic of data science.

Departmental Graduate Committee 2013-2015

- ★ Special committee for graduate student recruiting. Leading the effort, along with another colleague, to improve recruitment to the department, initially focusing on local schools in Virginia. This role serves a double-purpose in that it provides the opportunity to encourage a broad group of students to pursue graduate studies in engineering.

Faculty Candidate Tea Series Fall 2013

Systems and Information Engineering *Fall 2013 hiring cycle (3 searches)*
Chemical Engineering *Fall 2013 hiring cycle (2 searches)*

Georgia Institute of Technology, Atlanta, GA

Family Friendly Task Force Member 2012-2013

- ★ Worked as the sole graduate study body representative to identify keys areas that do not engender work life balances at the Institute on a campus wide committee.
- ★ Contributed to a document detailing recommendations for the university to improve the experience of working at the Institute. In particular, my sections detailed recommendations for for broadening graduate student and post-doc orientation educational focuses to better prepare them for life at tech and industry and academia afterward.

Campus Safety Task Force Member Spring 2011

- ★ Consulted with a mixed group of campus members (undergraduates to deans) on ways to improve campus safety.

Faculty Benefits Committee Member 2011-2012

- ★ Graduate Student Senate Representative.

Student Government Graduate Student Senator 2009-2011

- ★ Represented School of Electrical and Computer Engineering.
- ★ Voted on how to dole out the Student Activities Fee to student initiatives and organizations.
- ★ Ensured funding for arts organizations on campus.

Departmental Representative 2009-2013

- ★ Organized campus and tours for prospective graduate students.
- ★ Presented laboratory experiments to visiting elementary student groups and prospective students.

Princeton University, Princeton, NJ

Advisory Board, Student Representative 2008

- ★ Represented student interests for external advisory board meeting.
- ★ Emphasized to leading members in the field of engineering the importance of education reform to include a more broad and diverse student population.

Student Representative 2008

- ★ Related experience as an engineer at Princeton to all prospective engineering students.

PROFESSIONAL SERVICE AND MEMBERSHIP

Journal Service

IEEE Robotics and Automation Letters (RA-L). Associate Editor in HRI area.

P. Alves-Oliveira, M. Cakmak, G. Gordon, P. Kahn, A. LaViers, and V. Sarathy. (Eds.) "Creativity and Robots." Special Issue Research Topic *Frontiers*.

Conference Service

Planning Chair, Organizing Committee. *8th International Conference on Movement and Computing (MOCO)*. Chicago, IL. 2022.

International Program Committee (IPC) member for Art Jury in Art Gallery of the 13th ACM SIGGRAPH Conference and Exhibition on Computer Graphics and Interactive Techniques in Asia (SIGGRAPH Asia). 2020.

Program Committee. *25th International Symposium on Electronic Art (ISEA)*. 2019.

Program Committee. *Robotics: Science and Systems (RSS)*. Pittsburg, PA. 2018.

Program Committee. *Robotics: Science and Systems (RSS)*. Cambridge, MA. 2017.

Associate Editor. *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. Deajeon, Korea. September 2016.

Program Committee for the Work-in-Progress, Demo, and Poster Session *7th ACM/IEEE International Conference on Cyber-Physical Systems (ICCPS 2016)*. Vienna, Austria. April 2016.

Associate Editor. *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. Hamburg, Germany. September 2015.

International Program Committee. *IEEE Conference on Control Applications (CCA)*. Sydney, Australia. October 2015.

International Program Committee. *5th IFAC Conference on Analysis and Design of Hybrid Systems (ADHS)*. Atlanta, GA. October 2015.

International Program Committee. *IEEE Conference on Control Applications (CCA)*. Nice, France. October 2014.

Student Volunteer. *49th IEEE Conference on Decision and Control (CDC)*. Atlanta, GA. December 2010.

Referee Service

ACM/IEEE International Conference on Human-Robot Interaction (HRI)

Smart Culture – Arts and Culture Programme

International Conference on Movement and Computing (MOCO)

Techne: Research in Philosophy and Technology; Official Journal of the Society for Philosophy and Technology

Army Research Office (ARO)

Transactions on Human Robot Interaction (THRI)

International Journal of Social Robotics (SORO)

National Science Foundation (NSF) – ENG Directorate

Brain and Behavior Institute (BBI) – University of Maryland at College Park (UMD)

International Journal of Humanoid Robotics (IJHR)

IEEE Transactions on Human-Machine Systems (THMS)

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
National Science Foundation (NSF) – Graduate Research Fellowship Program (GRFP)
National Science Foundation (NSF) – CISE Directorate
IEEE Transactions on Robotics (T-RO)
IEEE International Conference on Robotics and Automation (ICRA)
IEEE American Control Conference (ACC)
IEEE Conference on Decision and Control (CDC)
World Congress of the International Federation of Automatic Control (IFAC)
International Symposium on Mathematical Theory of Networks and Systems (MTNS)

Institute for Electrical and Electronics Engineers (IEEE), Senior Member

IEEE Control Systems Society (CSS)
IEEE Robotics and Automation Society (RAS)
IEEE Systems, Man, and Cybernetics (SMC) Society
IEEE Education Society

American Society for Engineering Education (ASEE), Member

The College Art Association (CAA), Member

OUTREACH

DreamWakers Flashchat with classrooms in under-served communities

Harlem Link Charter School, New York, NY *Oct. 2015*
Stuart Pepper Middle, Brandenburg, KY *Sept. 2016*
Graham Area Schools, K-12, Tazewell County, VA *Dec. 2016*
Norge Elementary, Williamsburg, VA *Nov. 2017*
Muscatel Middle School, Rosemead, CA *Apr. 2018*
JFK School of Architecture and Construction Trades, Patterson, NJ *Apr. 2019*
New Bedford Whaling Museum apprentices, New Bedford, MA *Jul. 2019*
AVID program at HD Jacobs High School in Algonquin, IL *Jan. 2021*
DreamWakers Advisory Council (DWAC) 2021-23

East Kentucky Science Center (EKSC), Prestonsburg, KY

Drop-in science workshop designing pipe-cleaner robots based on story *Jun. 2019*
Held two workshops over two days in robotics and choreography *Jun. 2018*
Held day long workshop in robotics and choreography *Dec. 2016*

Southern Appalachian Science & Engineering Fair – Virtual Science Club via Zoom
September 2021

Kentucky Science & Engineering Fair at Eastern Kentucky University – Best of Fair,
Physical Sciences Judge *March 2020 and 2021*

Curious Jane, New York, NY – Held morning workshop on robotics and choreography
Sept. 2019

Laban/Bartnieff Institute of Movement Studies, New York, NY – Held lunchtime
workshop on robotics and choreography *Sept. 2019*

CTRL-Z Camp, Champaign, IL – Lab members demoed NAO robotic platform *Jun. 2016, 2017, 2019*

Urbana Neighborhood Connections Center (UNCC), Urbana, IL – Held week-long workshop focusing on choreography and robotics with 6th-9th grade girls from underrepresented groups *Jun. 2019*

MLK Elementary, Champaign, IL – Held day movement and robotics workshop for class of 5th graders as part of MechSE Department Outreach Program *Nov. 2017*

Girl Scouts Troop Visit, Champaign, IL *Nov. 2016.*

MechSE GAMES camp, Urbana, IL – Developed information and worksheet packet with graduate student Ashley Armstrong; held half day activity in robotics and choreography *Jun. 2016*

UVa Arts Mentors Program, Charlottesville, VA – Hosting an afternoon session, joint with Dance Program *Jan. 2015*

Society of Women Engineers (SWE), University of Virginia, High School Invitational, Academic Job Panel *Fall 2013 - Spring 2015*

Hosted group of high school girls from Holton-Arms School, Robotics, Automation, and Dance (RAD) Lab *Fall 2013*